

# Chapter 13

## LINES AND PLANES IN SPACE

### EXERCISE 13A.1

1 a i  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 \\ -4 \end{pmatrix} + t \begin{pmatrix} 1 \\ 4 \end{pmatrix}, t \in \mathbb{R}$

ii  $x = 3 + t, y = -4 + 4t$

$$\therefore t = x - 3 = \frac{y + 4}{4}$$

$$\therefore 4x - 12 = y + 4$$

$$\therefore 4x - y = 16$$

b i If the line has direction vector **b** perpendicular to  $\begin{pmatrix} -8 \\ 2 \end{pmatrix}$ , then

$$\mathbf{b} \cdot \begin{pmatrix} -8 \\ 2 \end{pmatrix} = 0$$

$\therefore \mathbf{b} = \begin{pmatrix} 2 \\ 8 \end{pmatrix}$  is a reasonable choice

$$\therefore \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 5 \\ 2 \end{pmatrix} + t \begin{pmatrix} 2 \\ 8 \end{pmatrix}, t \in \mathbb{R}$$

ii  $x = 5 + 2t, y = 2 + 8t$

$$\therefore t = \frac{x - 5}{2} = \frac{y - 2}{8}$$

$$\therefore 8x - 40 = 2y - 4$$

$$\therefore 8x - 2y = 36$$

$$\therefore 4x - y = 18$$

c i  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -6 \\ 0 \end{pmatrix} + t \begin{pmatrix} 3 \\ 7 \end{pmatrix}, t \in \mathbb{R}$

ii  $x = -6 + 3t, y = 7t$

$$\therefore t = \frac{x + 6}{3} = \frac{y}{7}$$

$$\therefore 7x + 42 = 3y$$

$$\therefore 7x - 3y = -42$$

d i Take  $(-1, 11)$  as our fixed point,

so  $\mathbf{a} = \begin{pmatrix} -1 \\ 11 \end{pmatrix}$ .

The direction vector  $\mathbf{b} = \begin{pmatrix} -3 - (-1) \\ 12 - 11 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$ .

$$\therefore \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 \\ 11 \end{pmatrix} + t \begin{pmatrix} -2 \\ 1 \end{pmatrix}, t \in \mathbb{R}$$

ii  $x = -1 - 2t, y = 11 + t$

$$\therefore t = \frac{x + 1}{-2} = y - 11$$

$$\therefore x + 1 = -2y + 22$$

$$\therefore x + 2y = 21$$

2  $x = -1 + 2t, y = 4 - t, t \in \mathbb{R}$

When  $t = 0, x = -1 + 2(0) = -1$  and  $y = 4 - 0 = 4$

$\therefore$  the point is  $(-1, 4)$ .

When  $t = 1, x = -1 + 2(1) = 1$  and  $y = 4 - 1 = 3$

$\therefore$  the point is  $(1, 3)$ .

When  $t = 3, x = -1 + 2(3) = 5$  and  $y = 4 - 3 = 1$

$\therefore$  the point is  $(5, 1)$ .

When  $t = -1, x = -1 + 2(-1) = -3$  and  $y = 4 - (-1) = 5$

$\therefore$  the point is  $(-3, 5)$ .

When  $t = -4, x = -1 + 2(-4) = -9$  and  $y = 4 - (-4) = 8$

$\therefore$  the point is  $(-9, 8)$ .

3 a If  $t + 2 = 3$  and  $1 - 3t = -2$ ,  
then  $t = 1$  and  $-3t = -3$   
 $\therefore t = 1$

Since  $t = 1$  in each case,  
 $(3, -2)$  lies on the line.

b If  $(k, 4)$  lies on  $x = 1 - 2t, y = 1 + t$ , then

$$k = 1 - 2t \text{ and } 4 = 1 + t$$

$$\therefore t = 3$$

$$\text{and } k = 1 - 6 = -5$$

4 a  $x(0) = 1$  and  $y(0) = 2$ ,

$\therefore$  the initial position is  $(1, 2)$

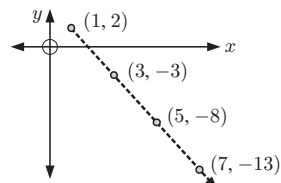
c In 1 second, the

$x$ -step is 2 and  $y$ -step is  $-5$ , which is

a distance of  $\sqrt{2^2 + (-5)^2} = \sqrt{29}$  cm

$\therefore$  the speed is  $\sqrt{29}$  cm s<sup>-1</sup>.

b



5 In parametric form:  $x = 1 - t, y = 5 + 3t, t \in \mathbb{R}$

$$\begin{aligned} \text{In Cartesian form: } t &= \frac{x-1}{-1} = \frac{y-5}{3} \\ \therefore 3x-3 &= -y+5 \\ \therefore 3x+y &= 8 \end{aligned}$$

### EXERCISE 13A.2

1 a The vector equation is  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 3 \\ -7 \end{pmatrix} + t \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}, t \in \mathbb{R}$

b The vector equation is  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} + t \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, t \in \mathbb{R}$

c Since the line is parallel to the  $X$ -axis, it has direction vector  $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$

$$\therefore \text{ the vector equation is } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, t \in \mathbb{R}$$

2 a The parametric equations are:

$$x = 5 + (-1)t, y = 2 + 2t, z = -1 + 6t$$

$$\therefore x = 5 - t, y = 2 + 2t, z = -1 + 6t, t \in \mathbb{R}$$

b The parametric equations are:

$$x = 0 + 2t, y = 2 + (-1)t, z = -1 + 3t$$

$$\therefore x = 2t, y = 2 - t, z = -1 + 3t, t \in \mathbb{R}$$

c Since the line is perpendicular to the  $XOY$  plane, it has direction vector  $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ .

$$\therefore \text{ the parametric equations are: } x = 3 + 0t, y = 2 + 0t, z = -1 + 1t$$

$$\therefore x = 3, y = 2, z = -1 + t, t \in \mathbb{R}$$

3 a  $\overrightarrow{AB} = \begin{pmatrix} -1-1 \\ 3-2 \\ 2-1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix} \therefore \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} + t \begin{pmatrix} -2 \\ 1 \\ 1 \end{pmatrix}, t \in \mathbb{R}$

b  $\overrightarrow{CD} = \begin{pmatrix} 3-0 \\ 1-1 \\ -1-3 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ -4 \end{pmatrix} \therefore \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix} + t \begin{pmatrix} 3 \\ 0 \\ -4 \end{pmatrix}, t \in \mathbb{R}$

c  $\overrightarrow{EF} = \begin{pmatrix} 1-1 \\ -1-2 \\ 5-5 \end{pmatrix} = \begin{pmatrix} 0 \\ -3 \\ 0 \end{pmatrix} \therefore \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 5 \end{pmatrix} + t \begin{pmatrix} 0 \\ -3 \\ 0 \end{pmatrix}, t \in \mathbb{R}$

d  $\overrightarrow{GH} = \begin{pmatrix} 5-0 \\ -1-1 \\ 3-1 \end{pmatrix} = \begin{pmatrix} 5 \\ -2 \\ 4 \end{pmatrix} \therefore \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} + t \begin{pmatrix} 5 \\ -2 \\ 4 \end{pmatrix}, t \in \mathbb{R}$

4 Given  $x = 1 - t, y = 3 + t, z = 3 - 2t$ :

a The line meets the  $XOY$  plane when  $z = 0 \therefore 3 - 2t = 0$

$$\therefore t = \frac{3}{2}$$

Then  $x = 1 - \frac{3}{2} = -\frac{1}{2}$  and  $y = 3 + \frac{3}{2} = \frac{9}{2}$ , so the point is  $(-\frac{1}{2}, \frac{9}{2}, 0)$ .

b The line meets the  $YOZ$  plane when  $x = 0 \therefore 1 - t = 0$

$$\therefore t = 1$$

Then  $y = 3 + 1 = 4$  and  $z = 3 - 2 = 1$ , so the point is  $(0, 4, 1)$ .

- c The line meets the  $XOZ$  plane when  $y = 0 \quad \therefore 3 + t = 0$   
 $\therefore t = -3$

Then  $x = 1 - (-3) = 4$  and  $z = 3 - 2(-3) = 9$ , so the point is  $(4, 0, 9)$ .

- 5 Given a line with equations  $x = 2 - t$ ,  $y = 3 + 2t$  and  $z = 1 + t$ ,  
 the distance to the point  $(1, 0, -2)$  is  $\sqrt{(2-t-1)^2 + (3+2t-0)^2 + (1+t+2)^2}$ .

But this distance =  $5\sqrt{3}$  units

$$\begin{aligned} \therefore \sqrt{(1-t)^2 + (3+2t)^2 + (t+3)^2} &= 5\sqrt{3} \\ \therefore (1-t)^2 + (3+2t)^2 + (t+3)^2 &= 75 \\ \therefore 1 - 2t + t^2 + 9 + 12t + 4t^2 + t^2 + 6t + 9 &= 75 \\ \therefore 6t^2 + 16t - 56 &= 0 \\ \therefore 3t^2 + 8t - 28 &= 0 \\ \therefore (3t+14)(t-2) &= 0 \\ \therefore t = -\frac{14}{3} \text{ or } t = 2 \end{aligned}$$

When  $t = 2$  the point is  $(0, 7, 3)$ , and when  $t = -\frac{14}{3}$  the point is  $(\frac{20}{3}, -\frac{19}{3}, -\frac{11}{3})$ .

### EXERCISE 13A.3

- 1  $L_1$  has direction vector  $\begin{pmatrix} 4 \\ -3 \end{pmatrix}$  and  $L_2$  has direction vector  $\begin{pmatrix} 5 \\ 4 \end{pmatrix}$ . If  $\theta$  is the angle between them,

$$\cos \theta = \frac{\left| \begin{pmatrix} 4 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 5 \\ 4 \end{pmatrix} \right|}{\sqrt{16+9}\sqrt{25+16}} = \frac{|20+(-12)|}{\sqrt{25} \times \sqrt{41}} = \frac{8}{\sqrt{25} \times \sqrt{41}}$$

$$\therefore \theta = \cos^{-1} \left( \frac{8}{\sqrt{25} \times \sqrt{41}} \right) \approx 75.5^\circ$$

$\therefore$  the required angle measures  $75.5^\circ$ .

- 2  $L_1$  has direction vector  $\begin{pmatrix} 12 \\ 5 \end{pmatrix}$  and  $L_2$  has direction vector  $\begin{pmatrix} 3 \\ -4 \end{pmatrix}$ . If  $\theta$  is the angle between them,

$$\cos \theta = \frac{\left| \begin{pmatrix} 12 \\ 5 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ -4 \end{pmatrix} \right|}{\sqrt{144+25}\sqrt{9+16}} = \frac{|36+(-20)|}{13 \times 5} = \frac{16}{65}$$

$$\therefore \theta = \cos^{-1} \left( \frac{16}{65} \right) \approx 75.7^\circ$$

- 3 Line 1 has direction vector  $\begin{pmatrix} 5 \\ -2 \end{pmatrix}$  and line 2 has direction vector  $\begin{pmatrix} 4 \\ 10 \end{pmatrix}$

$$\text{and } \begin{pmatrix} 5 \\ -2 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 10 \end{pmatrix} = 20 + (-20) = 0$$

$\therefore$  the lines are perpendicular.

- 4 a Line 1 has direction vector  $\begin{pmatrix} 3 \\ -16 \\ 7 \end{pmatrix}$  and line 2 has direction vector  $\begin{pmatrix} 3 \\ 8 \\ -5 \end{pmatrix}$ .

If  $\theta$  is the angle between them,

$$\cos \theta = \frac{\left| \begin{pmatrix} 3 \\ -16 \\ 7 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 8 \\ -5 \end{pmatrix} \right|}{\sqrt{9+256+49}\sqrt{9+64+25}} = \frac{|9-128-35|}{\sqrt{314}\sqrt{98}} = \frac{154}{\sqrt{314} \times \sqrt{98}}$$

$$\therefore \theta \approx 28.6^\circ$$

- b Since  $L_1 \perp L_3$ ,  $\begin{pmatrix} 3 \\ -16 \\ 7 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ -3 \\ x \end{pmatrix} = 0$

$$\therefore 48 + 7x = 0$$

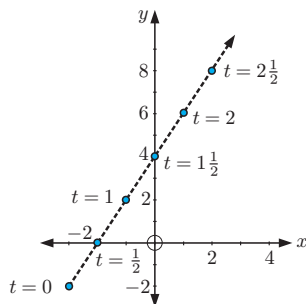
$$\therefore x = -\frac{48}{7}$$

**EXERCISE 13B.1**

- 1 a i** When  $t = 0$ ,  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -4 \\ 3 \end{pmatrix}$   
 $\therefore$  the object is at  $(-4, 3)$ .
 **ii** The velocity vector is  $\begin{pmatrix} 12 \\ 5 \end{pmatrix}$ .
 **iii** The speed is  $\sqrt{12^2 + 5^2} = 13 \text{ m s}^{-1}$
- b i** When  $t = 0$ ,  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ -6 \end{pmatrix}$   
 $\therefore$  the object is at  $(0, -6)$ .
 **ii** The velocity vector is  $\begin{pmatrix} 3 \\ -4 \end{pmatrix}$ .
 **iii** The speed is  $\sqrt{3^2 + (-4)^2} = 5 \text{ m s}^{-1}$
- c i** When  $t = 0$ ,  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -2 \\ -7 \end{pmatrix}$   
 $\therefore$  the object is at  $(-2, -7)$ .
 **ii** The velocity vector is  $\begin{pmatrix} -6 \\ -4 \end{pmatrix}$ .
 **iii** The speed is  $\sqrt{(-6)^2 + (-4)^2} = \sqrt{52} \text{ m s}^{-1}$
- d i** When  $t = 0$ ,  
 $x = 5$  and  $y = -5$   
 $\therefore$  the object is at  $(5, -5)$ .
 **ii** The velocity vector is  $\begin{pmatrix} 8 \\ 4 \end{pmatrix}$ .
 **iii** The speed is  $\sqrt{8^2 + 4^2} = \sqrt{80} \text{ m s}^{-1}$
- 2 a**  $\begin{pmatrix} 4 \\ -3 \end{pmatrix}$  has length  $\sqrt{4^2 + (-3)^2} = 5$   
 $\therefore 30\begin{pmatrix} 4 \\ -3 \end{pmatrix}$  has length 150  
 $\therefore$  the velocity vector is  $\begin{pmatrix} 120 \\ -90 \end{pmatrix}$ .
 **b**  $\begin{pmatrix} 24 \\ 7 \end{pmatrix}$  has length  $\sqrt{24^2 + 7^2} = 25$   
 $\therefore \frac{1}{2}\begin{pmatrix} 24 \\ 7 \end{pmatrix}$  has length 12.5  
 $\therefore$  the velocity vector is  $\begin{pmatrix} 12 \\ 3.5 \end{pmatrix}$ .
- c**  $2\mathbf{i} + \mathbf{j} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$  has length  $\sqrt{2^2 + 1^2} = \sqrt{5}$   
 $\therefore 10\sqrt{5}\begin{pmatrix} 2 \\ 1 \end{pmatrix}$  has length 50  
 $\therefore$  the velocity vector is  $\begin{pmatrix} 20\sqrt{5} \\ 10\sqrt{5} \end{pmatrix}$ .
- 3**  $-2\mathbf{i} + 5\mathbf{j} - 14\mathbf{k}$  has length  $\sqrt{(-2)^2 + 5^2 + (-14)^2} = \sqrt{4 + 25 + 196} = \sqrt{225} = 15$   
 $\therefore 6\begin{pmatrix} -2 \\ 5 \\ -14 \end{pmatrix}$  has length 90, so the velocity vector is  $\begin{pmatrix} -12 \\ 30 \\ -84 \end{pmatrix}$ .

**EXERCISE 13B.2**

- 1 a**  $\mathbf{r} = \mathbf{a} + t\mathbf{b}$   
 $\therefore \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -3 \\ -2 \end{pmatrix} + t\begin{pmatrix} 2 \\ 4 \end{pmatrix}, t \geq 0$   
 $\therefore \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -3+2t \\ -2+4t \end{pmatrix}$
- b** At  $t = 2.5$ ,  $-3 + 2t = -3 + 5 = 2$   
 and  $-2 + 4t = -2 + 10 = 8$   
 So, the position vector is  $\begin{pmatrix} 2 \\ 8 \end{pmatrix}$ .
- c i** When the car is due north,  $x = 0$ .  
 $\therefore -3 + 2t = 0$   
 $\therefore t = 1.5$  seconds
- ii** When the car is due west,  $y = 0$ .  
 $\therefore -2 + 4t = 0$   
 $\therefore t = 0.5$  seconds

**d**


- 2** Yacht A:  $\begin{pmatrix} x_A \\ y_A \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \end{pmatrix} + t\begin{pmatrix} 1 \\ -2 \end{pmatrix}$     Yacht B:  $\begin{pmatrix} x_B \\ y_B \end{pmatrix} = \begin{pmatrix} 1 \\ -8 \end{pmatrix} + t\begin{pmatrix} 2 \\ 1 \end{pmatrix}, t \geq 0$
- a** When  $t = 0$ ,  $\begin{pmatrix} x_A \\ y_A \end{pmatrix} = \begin{pmatrix} 4 \\ 5 \end{pmatrix}$   $\therefore$  A is at  $(4, 5)$   
 and  $\begin{pmatrix} x_B \\ y_B \end{pmatrix} = \begin{pmatrix} 1 \\ -8 \end{pmatrix}$   $\therefore$  B is at  $(1, -8)$ .
- b** For A, the velocity vector is  $\begin{pmatrix} 1 \\ -2 \end{pmatrix}$ , and for B it is  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ .
- c** Speed of A =  $\sqrt{1^2 + (-2)^2} = \sqrt{5} \text{ km h}^{-1}$ . Speed of B =  $\sqrt{2^2 + 1^2} = \sqrt{5} \text{ km h}^{-1}$ .

**d** A has direction vector  $\begin{pmatrix} 1 \\ -2 \end{pmatrix}$  and B has direction vector  $\begin{pmatrix} 2 \\ 1 \end{pmatrix}$ .  
 Since  $\begin{pmatrix} 1 \\ -2 \end{pmatrix} \bullet \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 2 - 2 = 0$ , the paths of the yachts are at right angles to each other.

**3 a** P's torpedo has position  $\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} -5 \\ 4 \end{pmatrix} + t \begin{pmatrix} 3 \\ -1 \end{pmatrix}$  and at  $t = 0$ , the time is 1:34 pm  
 $\therefore x_1(t) = -5 + 3t, y_1(t) = 4 - t$ .

**b** Speed =  $\sqrt{3^2 + (-1)^2} = \sqrt{10} \text{ km min}^{-1}$

**c** Q fires its torpedo after  $a$  minutes.  
 $\therefore$  at time  $t$ , its torpedo has travelled for  $(t - a)$  minutes.

$$\therefore \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} 15 \\ 7 \end{pmatrix} + (t - a) \begin{pmatrix} -4 \\ -3 \end{pmatrix}, t \geq a$$

$$\therefore x_2(t) = 15 - 4(t - a) \text{ and } y_2(t) = 7 - 3(t - a)$$

**d** They meet when  $x_1(t) = x_2(t)$  and  $y_1(t) = y_2(t)$   
 $\therefore -5 + 3t = 15 - 4(t - a)$  and  $4 - t = 7 - 3(t - a)$   
 $\therefore 7t - 4a = 20 \dots (1)$  and  $2t - 3a = 3 \dots (2)$

$$\begin{array}{rcl} \text{Solving simultaneously,} & 21t - 12a = 60 & \{3 \times (1)\} \\ & -8t + 12a = -12 & \{-4 \times (2)\} \\ \text{adding} & 13t & = 48 \end{array}$$

$$\therefore t = \frac{48}{13} \text{ and } 7 \left( \frac{48}{13} \right) - 4a = 20$$

$$\therefore t \approx 3.6923 \qquad \therefore 5.8462 = 4a$$

$$\therefore t \approx 3 \text{ min } 41.54 \text{ sec} \qquad \therefore a \approx 1.4615 \approx 1 \text{ min } 27.7 \text{ sec}$$

So, as  $a \approx 1.4615$ , Q fired at 1:35:28 pm, and the explosion occurred at 1:37:42 pm.

**4 a**  $\vec{AB} = \begin{pmatrix} 3 - 6 \\ 10 - 9 \\ 2.5 - 3 \end{pmatrix} = \begin{pmatrix} -3 \\ 1 \\ -0.5 \end{pmatrix}$

**b**  $|\vec{AB}| = \sqrt{(-3)^2 + 1^2 + (-0.5)^2} = \sqrt{10.25} \text{ km}$

**c**  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 6 \\ 9 \\ 3 \end{pmatrix} + t \begin{pmatrix} -3 \\ 1 \\ -0.5 \end{pmatrix}, t \in \mathbb{R}$

The helicopter travels  $\sqrt{10.25} \text{ km}$  in 10 minutes.  
 $\therefore$  the helicopter's speed is  $6 \times \sqrt{10.25} \approx 19.2 \text{ km h}^{-1}$ .

**d** If  $z = 0, 3 + (-0.5)t = 0$   
 $\therefore t = 6$

$t = 1$  represents 10 minutes, so  $t = 6$  represents 60 minutes.  
 $\therefore$  the helicopter lands on the helipad after 1 hour.

**EXERCISE 13B.3**

**1 a**  $6i - 6j$

**b** The length of  $\begin{pmatrix} -3 \\ 4 \end{pmatrix} = \sqrt{(-3)^2 + 4^2} = \sqrt{25} = 5$

As the speed is  $10 \text{ km h}^{-1}$ , the liner has velocity vector  $2 \begin{pmatrix} -3 \\ 4 \end{pmatrix} = \begin{pmatrix} -6 \\ 8 \end{pmatrix}$ .

$\therefore$  the liner has position  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 6 \\ -6 \end{pmatrix} + t \begin{pmatrix} -6 \\ 8 \end{pmatrix}, t \geq 0, t$  in hours.

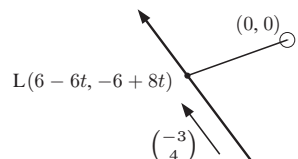
**c** The liner is due east when  $y = 0$   
 $\therefore -6 + 8t = 0$

$$\therefore \text{at } t = \frac{3}{4} \text{ hour}$$

**d** The liner L is nearest the fishing boat O when  $\vec{OL} \perp \begin{pmatrix} -3 \\ 4 \end{pmatrix}$ .

$$\therefore \vec{OL} \bullet \begin{pmatrix} -3 \\ 4 \end{pmatrix} = 0$$

$$\therefore \begin{pmatrix} 6 - 6t \\ -6 + 8t \end{pmatrix} \bullet \begin{pmatrix} -3 \\ 4 \end{pmatrix} = 0$$



$$\therefore (-18 + 18t) + (-24 + 32t) = 0$$

$$\therefore 50t = 42$$

$$\therefore t = 0.84 \text{ hours} = 50.4 \text{ minutes}$$

$$\text{and when } t = 0.84, L = \begin{pmatrix} 6 - 6(0.84) \\ -6 + 8(0.84) \end{pmatrix} = \begin{pmatrix} 0.96 \\ 0.72 \end{pmatrix}$$

$\therefore$  the liner is closest to the fishing boat after 0.84 hours or 50.4 minutes, when it is at (0.96, 0.72).

**2 a**  $|b| = \sqrt{(-3)^2 + (-1)^2} = \sqrt{10}$

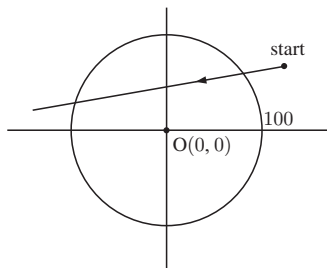
As the speed is  $40\sqrt{10}$  km h<sup>-1</sup>, the velocity vector is  $40\begin{pmatrix} -3 \\ -1 \end{pmatrix} = \begin{pmatrix} -120 \\ -40 \end{pmatrix}$ .

**b**  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 200 \\ 100 \end{pmatrix} + t\begin{pmatrix} -120 \\ -40 \end{pmatrix}, t \geq 0 \quad \{t = 0 \text{ at } 12:00 \text{ noon}\}$

**c** At 1:00 pm,  $t = 1$  and  $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 200-120 \\ 100-40 \end{pmatrix} = \begin{pmatrix} 80 \\ 60 \end{pmatrix}$

**d** The distance from  $O(0, 0)$  to  $P_1(80, 60)$  is  $\left| \begin{pmatrix} 80 \\ 60 \end{pmatrix} \right| = \sqrt{80^2 + 60^2} = 100$  km,  
which is when it becomes visible to radar. {within 100 km of  $O(0, 0)$ }

**e**



A general point on the path is  $P(200 - 120t, 100 - 40t)$ .

$$\text{Now } \vec{OP} = \begin{pmatrix} 200-120t \\ 100-40t \end{pmatrix},$$

$$\text{and for the closest point } \vec{OP} \bullet \begin{pmatrix} -3 \\ -1 \end{pmatrix} = 0$$

$$\therefore -3(200 - 120t) - 1(100 - 40t) = 0$$

$$\therefore -700 + 400t = 0$$

$$\therefore t = \frac{7}{4} = 1\frac{3}{4} \text{ hours}$$

$\therefore$  the time when the aircraft is closest is 1:45 pm, and

$$\text{at this time } \vec{OP} = \begin{pmatrix} 200-120(\frac{7}{4}) \\ 100-40(\frac{7}{4}) \end{pmatrix} = \begin{pmatrix} -10 \\ 30 \end{pmatrix}$$

$$\therefore d_{\min} = \sqrt{(-10)^2 + 30^2} \approx 31.6 \text{ km}$$

**f** It disappears from radar when  $|\vec{OP}| = 100$  and  $t > 1\frac{3}{4}$

$$\therefore \sqrt{(200 - 120t)^2 + (100 - 40t)^2} = 100$$

$$\therefore 40000 - 48000t + 14400t^2 + 10000 - 8000t + 1600t^2 = 10000$$

$$\therefore 16000t^2 - 56000t + 40000 = 0$$

$$\therefore 16t^2 - 56t + 40 = 0 \quad \{\div 1000\}$$

$$\therefore 2t^2 - 7t + 5 = 0 \quad \{\div 8\}$$

$$\therefore (2t - 5)(t - 1) = 0$$

$$\therefore t = \frac{5}{2} \quad \{\text{as } t > 1\frac{3}{4}\}$$

So, the aircraft disappears from the radar screen  $2\frac{1}{2}$  hours after noon, or at 2:30 pm.

**3 a** At A,  $y = 0$                       At B,  $x = 0$

$$\therefore 2x = 36 \quad \therefore 3y = 36$$

$$\therefore x = 18 \quad \therefore y = 12$$

So A is (18, 0) and B is (0, 12).

**b**  $2x + 3y = 36$

$$\therefore 3y = 36 - 2x$$

$$\therefore y = \frac{36 - 2x}{3}$$

$\therefore$  any point R on the railway track can

$$\text{be written } R\left(x, \frac{36 - 2x}{3}\right).$$

**c**  $\vec{PR} = \begin{pmatrix} x - 4 \\ \frac{36 - 2x}{3} - 0 \end{pmatrix} = \begin{pmatrix} x - 4 \\ \frac{36 - 2x}{3} \end{pmatrix}$

$$\vec{AB} = \begin{pmatrix} 0 - 18 \\ 12 - 0 \end{pmatrix} = \begin{pmatrix} -18 \\ 12 \end{pmatrix}$$